

Outlier-resistant inference without jump-detection filter *

Shoichi Eguchi¹ Hiroki Masuda²

¹Faculty of Information Science and Technology, Osaka Institute of Technology

²Graduate School of Mathematical Sciences, University of Tokyo

Fall School “Time Series, Random Fields and beyond”

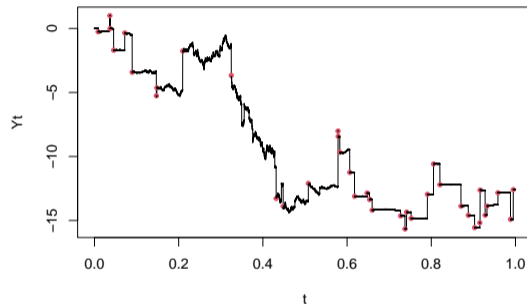
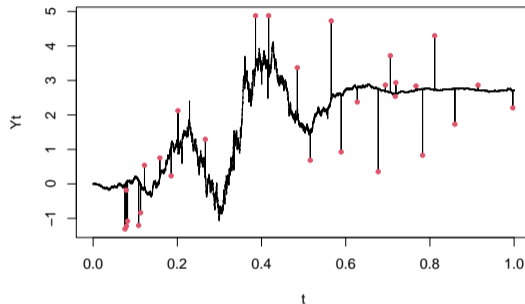
Ulm University

September 26, 2024 †

*Supported by JSPS KAKENHI (22H01139) and by JST CREST (JPMJCR2115).

†This version: September 26, 2024

Continuous-time volatility modeling



- Want to focus on the black line.
- Regarding the red points as external enemy.

Objective

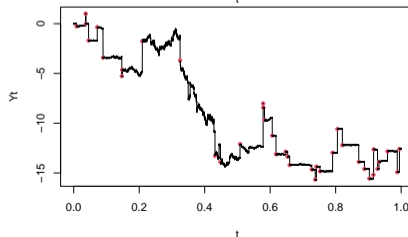
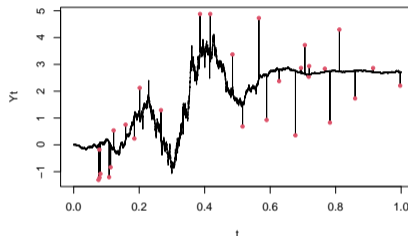
Robust parametric inference for the volatility, ignoring **discontinuous contaminations**

$$\begin{cases} Y_t^* = Y_0^* + \int_0^t \mu_{s-} ds + \int_0^t \sigma(X_{s-}^*, \theta) dw_s + J_t \\ X_t^* = X_0^* + \int_0^t \mu'_{s-} ds + \int_0^t \sigma'_{s-} dw'_s + J'_t \end{cases}$$

$$\begin{cases} Y_t = Y_t^* + \sum_{j=1}^n \Upsilon_j I(t = t_j) \\ X_t = X_t^* + \sum_{j=1}^n \Upsilon'_j I(t = t_j) \end{cases}$$

$$\stackrel{\text{Obs.}}{\implies} \{(X_{t_j}, Y_{t_j})\}_{j=0}^n, \quad t_j = jT/n =: jh$$

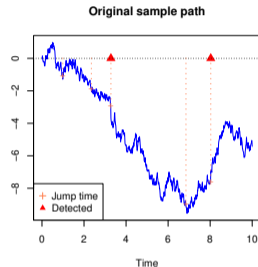
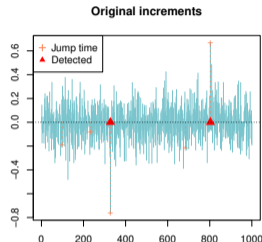
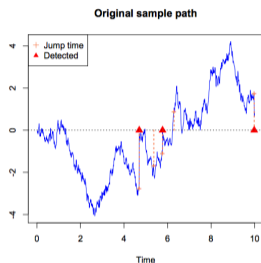
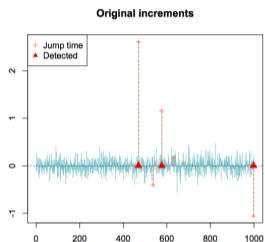
- Asymptotic inference for θ
- Parametric diffusion coeff. $\sigma(x, \theta)$



Outline

- 1 Backgrounds
- 2 Robustified Gaussian quasi-likelihood
- 3 Asymptotics
- 4 Numerical experiments
- 5 Concluding remarks

How to handle jumps



- **Pruning (Selection) type** for both ergodic and non-ergodic cases:

$$\text{Ignore } Y_{t_j} - Y_{t_{j-1}} \text{ if } |Y_{t_j} - Y_{t_{j-1}}| \geq Ch^\kappa$$

- **Local jump detection filter:** [Shimizu and Yoshida, 2006], [Ogihara and Yoshida, 2011], ...
- **Self-normalized statistics bases test** [Masuda and Uehara, 2021]: Remove large increments
- **Global jump detection filter** [Inatsugu and Yoshida, 2021]: Order-statistics based “deformation”

Our interest: **simple and (relatively) tuning-resistant way?**

$$\begin{aligned}
 Y_t^* &= Y_0^* + \int_0^t \mu_{s-} ds + \int_0^t \sigma(X_{s-}^*, \theta) dw_s + J_t, & X_t^* &= X_0^* + \int_0^t \mu'_{s-} ds + \int_0^t \sigma'_{s-} dw'_s + J'_t, \\
 Y_t &= Y_t^* + \sum_{j=1}^n \Upsilon_j I(t = t_j), & X_t &= X_t^* + \sum_{j=1}^n \Upsilon'_j I(t = t_j) \xrightarrow{\text{Obs.}} \{(X_{t_j}, Y_{t_j})\}_{j=0}^n, \quad t_j = jT/n =: jh
 \end{aligned}$$

- Application of **the density-power divergence** [Basu et al., 1998]? (like the Box-Cox trans.)

$$(f; g) \mapsto \int \left(f^{1+\lambda} - \left(1 + \frac{1}{\lambda}\right) f^\lambda g + \frac{1}{\lambda} g^{1+\lambda} \right) d\mu \geq 0$$

- Converges to the Kullback-Leibler divergence (from g to f) for $\lambda \downarrow 0$.

- Asymptotic inference theory with effectively ignoring contaminations?
- No heavy computational loading, and no sensitive fine-tuning.

Previous studies for **ergodic diffusion** ($T = nh \rightarrow \infty$)

- [Lee and Song, 2013] considered $dY_t = \mu(Y_t, \theta)dt + \sigma dw_t$ and proved

$$\left(\sqrt{nh}(\hat{\theta}_n(\lambda) - \theta_0), \sqrt{n}(\sigma_n(\lambda) - \sigma_0) \right) \xrightarrow{\mathcal{L}} N(0, V_0(\lambda))$$

through minimizing the the (explicit) Euler-scheme based objective function:

$$(\theta, \sigma) \mapsto \int \phi(y; Y_{t_{j-1}} + \mu_{j-1}(\theta)h, \sigma^2 h)^{1+\lambda} dy - \left(1 + \frac{1}{\lambda}\right) \sum_{j=1}^n \phi(Y_{t_j}; Y_{t_{j-1}} + \mu_{j-1}(\theta)h, \sigma^2 h)^\lambda$$

- [Song, 2017] similarly considered $dY_t = \mu(Y_t, \theta)dt + \sigma(Y_t, \gamma)dw_t$ and proved the consistency

$$(\hat{\theta}_n(\lambda), \sigma_n(\lambda)) \xrightarrow{P} (\theta_0, \sigma_0).$$

- Yet, they/he did no theoretical consideration about **what happens under contaminations**.

1 Backgrounds

2 Robustified Gaussian quasi-likelihood

3 Asymptotics

4 Numerical experiments

5 Concluding remarks

- We are given a complete filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in T}, P)$.

Setup: Stochastic dynamic regression **with jumps and spikes**

$$Y_t^* = Y_0^* + \int_0^t \mu_{s-} ds + \int_0^t \sigma(X_{s-}^*, \theta) dw_s + J_t, \quad X_t^* = X_0^* + \int_0^t \mu'_{s-} ds + \int_0^t \sigma'_{s-} dw'_s + J'_t,$$

$$Y_t = Y_t^* + \sum_{j=1}^n \Upsilon_j I(t = t_j), \quad X_t = X_t^* + \sum_{j=1}^n \Upsilon'_j I(t = t_j) \xrightarrow{\text{Obs.}} \{(X_{t_j}, Y_{t_j})\}_{j=0}^n, \quad t_j = jT/n =: jh$$

- Jumps $J_t = \sum_{0 < s \leq t} \Delta Y_s^*$ ($\Delta Y_s^* := Y_s^* - Y_{s-}^*$) and $J'_t = \sum_{0 < s \leq t} \Delta X_s^*$
- Spikes $\Upsilon_j = \Upsilon_{n,j}$ and $\Upsilon'_j = \Upsilon'_{n,j}$ are \mathcal{F}_{t_j} -m'ble r.v.'s.
- Fake **Gaussian quasi-likelihood** (QL) based on the Euler approx. $Y_{t_j} \stackrel{P_\theta}{\approx} Y_{t_{j-1}} + h\sigma_{j-1}(\theta)\Delta_j w$:

$$\mathbb{H}_n(\theta) := \sum_{j=1}^n \log \phi_d(Y_{t_j}; Y_{t_{j-1}}, hS_{j-1}(\theta)) =: \sum_{j=1}^n \log \phi_j(\theta)$$

- $S := \sigma^{\otimes 2}$, $f_{j-1}(\theta) := f(X_{t_{j-1}}, Y_{t_{j-1}}; \theta)$.

Density-power weighting for Gaussian quasi-(log-)likelihood

$$(f; g) \mapsto \int \left(f^{1+\lambda} - \left(1 + \frac{1}{\lambda}\right) f^\lambda g + \frac{1}{\lambda} g^{1+\lambda} \right) d\mu =: \text{Const.} + \int f^{1+\lambda} d\mu - \left(1 + \frac{1}{\lambda}\right) \int f^\lambda g d\mu \geq 0$$

- Applying the above density-power form ($\phi_{j-1}(y; \theta) := \phi(y; Y_{t_{j-1}}, hS_{j-1}(\theta))$),

$$\begin{aligned} \theta &\mapsto \sum_{j=1}^n \left(\frac{1}{\lambda} \phi_j(\theta)^\lambda - \frac{1}{\lambda+1} \int \phi_{j-1}(y; \theta)^{\lambda+1} dy \right) \\ &= \sum_{j=1}^n \left(\frac{1}{\lambda} \phi_j(\theta)^\lambda - h^{-d\lambda/2} \frac{(2\pi)^{-d\lambda/2}}{(\lambda+1)^{1+d/2}} \det(S_{j-1}(\theta))^{-\lambda/2} \right) \end{aligned}$$

Definition 2.1 (Density-power Gaussian QL ($\phi(\cdot); = \phi_d(\cdot; 0, I_d); 0 < \lambda \leq 1$))

$$\mathbb{H}_n(\theta; \lambda) = \sum_{j=1}^n \det(S_{j-1}(\theta))^{-\lambda/2} \left(\frac{1}{\lambda} \phi(S_{j-1}(\theta)^{-1/2} h^{-1/2} \Delta_j Y)^\lambda - \frac{(2\pi)^{-d\lambda/2}}{(\lambda+1)^{1+d/2}} \right)$$

1 Backgrounds

2 Robustified Gaussian quasi-likelihood

3 Asymptotics

4 Numerical experiments

5 Concluding remarks

- The best possible phenomenon for any regular estimator $\tilde{\theta}_n$ is well-known [Gobet, 2001]:

$$\sqrt{n}(\tilde{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} MN \left(0, \left(\frac{1}{2T} \int_0^T \text{trace} ((S^{-1}(\partial_\theta S) S^{-1}(\partial_\theta S))_t) dt \right)^{-1} \right)$$

- Our $\hat{\theta}_n(\lambda)$ has an asymptotic mixed normality **for each** $\lambda > 0$.

Regularity conditions in brief

$$Y_t^* = Y_0^* + \int_0^t \mu_{s-} ds + \int_0^t \sigma(X_{s-}^*, \theta) dw_s + J_t, \quad X_t^* = X_0^* + \int_0^t \mu'_{s-} ds + \int_0^t \sigma'_{s-} dw'_s + J'_t,$$

$$Y_t = Y_t^* + \sum_{j=1}^n \Upsilon_j I(t = t_j), \quad X_t = X_t^* + \sum_{j=1}^n \Upsilon'_j I(t = t_j) \xrightarrow{\text{Obs.}} \{(X_{t_j}, Y_{t_j})\}_{j=0}^n, \quad t_j = jT/n =: jh$$

Assumption 3.1

- ① Smoothness and non-degeneracy of $(x, \theta) \mapsto S(x, \theta)$
- ② Integrability of (μ, X, J)
- ③ **Probabilistic structures of finite-activity jumps**
- ④ **Probabilistic structures of spike noise**
- ⑤ Identifiability, and positive definiteness of the asymptotic covariance

Asymptotic mixed normality for fixed $\lambda > 0$

Theorem 3.2

$$\sqrt{n}(\hat{\theta}_n(\lambda) - \theta_0) \xrightarrow{\mathcal{L}} MN_p(0, \Gamma_0(\lambda)^{-1} \Sigma_0(\lambda) \Gamma_0(\lambda)^{-1})$$

$$\begin{aligned} \Sigma_0^{(k,l)}(\lambda) := & \frac{(2\pi)^{-d\lambda}}{4T} \int_0^T \det(S_t)^{-\lambda/2} \times \left\{ (2\lambda(2\lambda+1))^{-(1+d/2)} - \lambda^2(\lambda+1)^{-(2+d)} \right. \\ & \times \text{trace}((S^{-1}\partial_{\theta_k} S)_t) \text{trace}((S^{-1}\partial_{\theta_l} S)_t) \\ & \left. + 2(2\lambda+1)^{-(1+d/2)} \text{trace}((S^{-1}(\partial_{\theta_k} S)S^{-1}(\partial_{\theta_l} S))_t) \right\} dt, \end{aligned}$$

$$\begin{aligned} \Gamma_0^{(k,l)}(\lambda) := & \frac{(2\pi)^{-d\lambda/2}}{(\lambda+1)^{1+d/2}} \times \frac{1}{2T} \int_0^T \det(S_t)^{-\lambda/2} \left\{ (1-\lambda) \text{trace}((S^{-1}(\partial_{\theta_k} S)S^{-1}(\partial_{\theta_l} S))_t) \right. \\ & \left. - \lambda^2 \text{trace}((S^{-1}(\partial_{\theta_k} S))_t) \text{trace}((S^{-1}(\partial_{\theta_l} S))_t) \right\} dt \quad (\text{We wrote } f_t := f(\mathbf{X}_t^*, \theta_0)). \end{aligned}$$

- $\lim_{\lambda \downarrow 0} \Sigma_0(\lambda) = \lim_{\lambda \downarrow 0} \Gamma_0(\lambda) = \frac{1}{2T} \int_0^T \text{trace}((S^{-1}(\partial_{\theta_k} S)S^{-1}(\partial_{\theta_l} S))_t) dt$ a.s. (Fisher-info. matrix)

1 Backgrounds

2 Robustified Gaussian quasi-likelihood

3 Asymptotics

4 Numerical experiments

5 Concluding remarks

Simulation designs: Gaussian additive processes with contamination

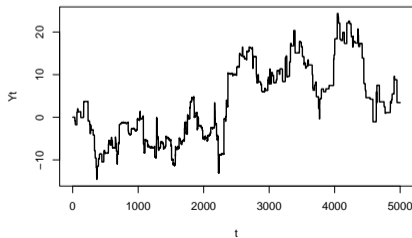
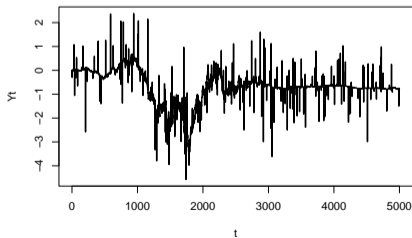
• Model: $Y_t = \int_0^t \exp \left\{ \frac{1}{2} (\theta_1 X_{1,s} + \theta_2 X_{2,s}) \right\} dw_s, \quad (X_{1,t_j}, X_{2,t_j}) = (\cos(2j\pi/n), \sin(2j\pi/n))$

① Spike noise: $Y_{t_j} = Y_{o,t_j}^i + p_j Y_{c,t_j}, \quad t_j = j/n \in [0, 1]$

- $Y_{c,t_1}, \dots, Y_{c,t_n} \sim \text{i.i.d. } N(0, 1); \quad p_0, p_1, \dots, p_n \sim \text{i.i.d. Bernoulli}(0.05) \quad [5\% \text{ contamination}],$
 $(\theta_{1,0}, \theta_{0,2}) = (-2, 3), \quad n = 5000, \quad \#MC = 1000.$

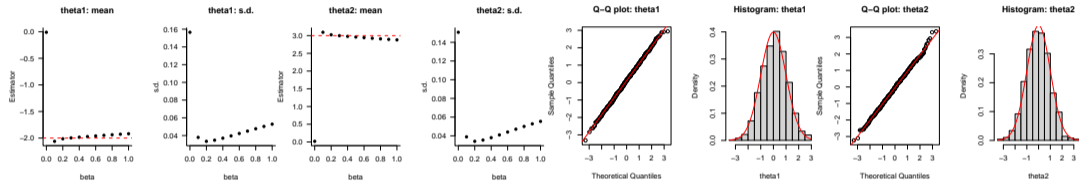
② Compound Poisson jumps: $Y_t = \int_0^t \exp \left\{ \frac{1}{2} (-2X_{1,s} + 3X_{2,s}) \right\} dw_s + J_t, \quad Y_0 = 0$

- $\mathcal{L}(J_t) = CP(\lambda t, N(0, 5))$ with $\lambda = 0.05n; \quad n = 5000, \quad \#MC = 1000 \quad [250 \text{ jumps in average}]$

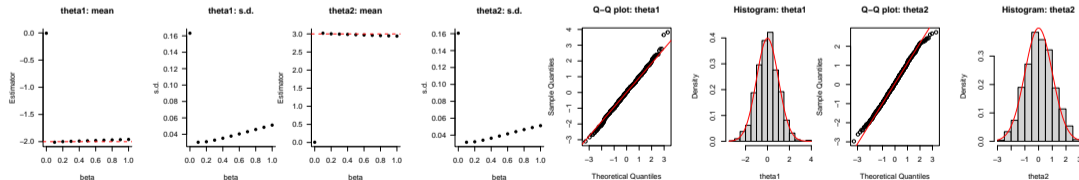


- Checking the robustness

- Spike case

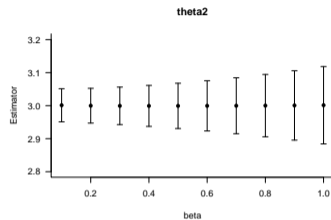
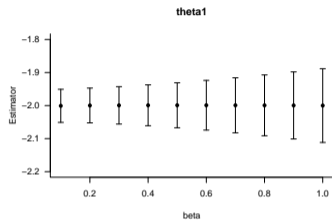


- Jump case

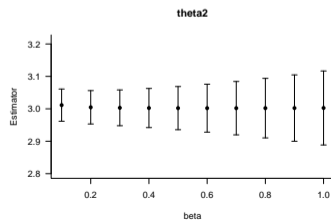
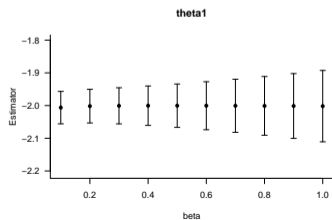


- Plots of averaged estimates with confidence intervals (Theorem 3.2); $(\theta_{1,0}, \theta_{0,2}) = (-2, 3)$.

1 Spike case



2 Jump case



1 Backgrounds

2 Robustified Gaussian quasi-likelihood

3 Asymptotics

4 Numerical experiments

5 Concluding remarks

Summary: Robust volatility inference with single fine tuning

$$\begin{aligned}
 Y_t^* &= Y_0^* + \int_0^t \mu_{s-} ds + \int_0^t \sigma(X_{s-}^*, \theta) dw_s + J_t, & X_t^* &= X_0^* + \int_0^t \mu'_{s-} ds + \int_0^t \sigma'_{s-} dw'_s + J'_t, \\
 Y_t &= Y_t^* + \sum_{j=1}^n \Upsilon_j I(t = t_j), & X_t &= X_t^* + \sum_{j=1}^n \Upsilon'_j I(t = t_j) \xrightarrow{\text{Obs}} \{(X_{t_j}, Y_{t_j})\}_{j=0}^n, \quad t_j = jT/n =: jh
 \end{aligned}$$

Explicit density-power Gaussian QLF

$$\begin{aligned}
 \mathbb{H}_n(\theta; \lambda) &:= \sum_{j=1}^n \det(S_{j-1}(\theta))^{-\lambda/2} \left(\frac{1}{\lambda} \phi(S_{j-1}(\theta)^{-1/2} h^{-1/2} \Delta_j Y)^\lambda - \frac{(2\pi)^{-d\lambda/2}}{(\lambda + 1)^{1+d/2}} \right) \\
 \sqrt{n}(\hat{\theta}_n(\lambda) - \theta_0) &\xrightarrow{\mathcal{L}} MN_p \left(0, \Gamma_0(\lambda)^{-1} \Sigma_0(\lambda) \Gamma_0(\lambda)^{-1} \right)
 \end{aligned}$$

Concluding remarks I

- **Controlling the tuning parameter** as $\lambda = \lambda_n \downarrow 0$ at appropriate rate:

$$\sqrt{n}(\hat{\theta}_n(\lambda_n) - \theta_0) \xrightarrow{\mathcal{L}} MN_p \left(0, \left(\frac{1}{2T} \int_0^t \text{trace} \left((S^{-1}(\partial_\theta S) S^{-1}(\partial_\theta S)(X_t, \theta_0)) \right) dt \right)^{-1} \right)$$

- For construction of BIC type model selection criterion based on $\mathbb{H}_n(\theta; \lambda)$ (Ongoing).
- Applicable to **Hölder based divergence**, also known as γ -divergence, as well.
 - [Windham, 1995] and [Jones et al., 2001]; also [Fujisawa and Eguchi, 2008].
 - Approx. martingale-estimating-function version can effectively handle heteroskedasticity.

$$\mathbb{H}_n(\theta; \lambda) := \sum_{j=1}^n \det(S_{j-1}(\theta))^{-\lambda/(2(\lambda+1))} \phi(S_{j-1}(\theta)^{-1/2} h^{-1/2} \Delta_j Y)^\lambda.$$

Concluding remarks II

- The approximation technique will apply to **various other “Gaussian type” QL inferences**:

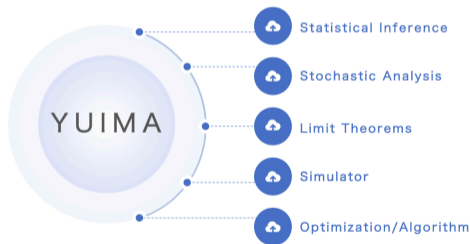
$$\mathbb{H}_n(\theta) \leftarrow \sum_{j=1}^n \log \phi_d(Y_{t_j}; \mu_h(X_{t_{j-1}}, \theta), \Sigma_h(X_{t_{j-1}}, \theta; h))$$

$$\mu_h(X_{t_{j-1}}, \theta) \approx E_{\theta}^{j-1}[Y_{t_j}], \quad \Sigma_h(X_{t_{j-1}}, \theta; h) \approx \text{Cov}_{\theta}^{j-1}[Y_{t_j}],$$

such as location-scale time series model, ergodic diffusion, **ergodic Lévy driven SDE¹**, small diffusion, small-Lévy driven SDE, etc.

Concluding remarks III

- Implementation of “qmlerobust” in yuima R package [Brouste et al., 2014] (by S. Eguchi);
User input: T , n , $\sigma(x, \theta)$, and $\lambda \in (0, 1]$ (with the rule of thumb “use $\lambda = 0.2 \sim 0.1$ ”).



ASSESSMENT

- Mean squared error analysis
- Goodness-of-fit testing
- Residual analysis
- Information criteria, ...

ANALYSIS & ASYMPTOTICS

- Parameter estimation
- Quantitative confidence set
- Prediction uncertainty, ...



IDEA

- Sometimes intuitive
- Ideally simple enough and practical

MODEL BUILDING

- Randomly perturbed dynamical system
- Linear and/or non-linear
- Noise character, ...

¹Essentially requires different consideration! Ongoing.

Related references I



Basu, A., Harris, I. R., Hjort, N. L., and Jones, M. C. (1998).
Robust and efficient estimation by minimising a density power divergence.
Biometrika, 85(3):549–559.



Brouste, A., Fukasawa, M., Hino, H., Iacus, S. M., Kamatani, K., Koike, Y., Masuda, H., Nomura, R., Ogihara, T., Shimizu, Y., Uchida, M., and Yoshida, N. (2014).
The yuima project: A computational framework for simulation and inference of stochastic differential equations.
Journal of Statistical Software, 57(4):1–51.



Fujisawa, H. and Eguchi, S. (2008).
Robust parameter estimation with a small bias against heavy contamination.
J. Multivariate Anal., 99(9):2053–2081.



Gobet, E. (2001).
Local asymptotic mixed normality property for elliptic diffusion: a Malliavin calculus approach.
Bernoulli, 7(6):899–912.



Inatsugu, H. and Yoshida, N. (2021).
Global jump filters and quasi-likelihood analysis for volatility.
Ann. Inst. Statist. Math., 73(3):555–598.



Jones, M. C., Hjort, N. L., Harris, I. R., and Basu, A. (2001).
A comparison of related density-based minimum divergence estimators.
Biometrika, 88(3):865–873.

Related references II



Lee, S. and Song, J. (2013).

Minimum density power divergence estimator for diffusion processes.

Ann. Inst. Statist. Math., 65(2):213–236.



Masuda, H. and Uehara, Y. (2021).

Estimating diffusion with compound Poisson jumps based on self-normalized residuals.

J. Statist. Plann. Inference, 215:158–183.



Ogihara, T. and Yoshida, N. (2011).

Quasi-likelihood analysis for the stochastic differential equation with jumps.

Stat. Inference Stoch. Process., 14(3):189–229.



Shimizu, Y. and Yoshida, N. (2006).

Estimation of parameters for diffusion processes with jumps from discrete observations.

Stat. Inference Stoch. Process., 9(3):227–277.



Song, J. (2017).

Robust estimation of dispersion parameter in discretely observed diffusion processes.

Statist. Sinica, 27(1):373–388.



Windham, M. P. (1995).

Robustifying model fitting.

J. Roy. Statist. Soc. Ser. B, 57(3):599–609.