**Exercise 1:** Let Y be a  $Gamma(n, \lambda)$ -distributed random variable with  $n \ge 2$ . Consequently, Y has the density

$$f(x) = \frac{\lambda^n}{(n-1)!} x^{n-1} e^{-\lambda x} \mathbf{1}_{(0,\infty)}(x).$$

Furthermore, let  $X_1, \ldots, X_n$  be a random sample with  $X_1 \sim Exp(\lambda)$ .

- a) Find  $E\left[\frac{1}{Y}\right]$
- b) Find the Expectation of  $\overline{X}$  as well as the expectation of  $\frac{1}{\overline{X}}$ . Is  $\frac{1}{\overline{X}}$  an unbiased estimator for  $\lambda$ ? (Hint: Sheet 5 Exercise 2.)
- c) For which  $a_n$  is  $\frac{a_n}{\overline{X}}$  an unbiased estimator for  $\lambda$ ?

#### Solution:

a) We can show that

$$E\left[\frac{1}{Y}\right] = \int_0^\infty \frac{1}{y} \lambda^n y^{n-1} e^{-\lambda y} \frac{1}{(n-1)!} dy$$
$$= \frac{\lambda}{n-1} \int_0^\infty \lambda^{n-1} y^{n-2} e^{-\lambda y} \frac{1}{(n-2)!} dy$$
$$= \frac{\lambda}{n-1}$$

b) For the expectation of  $\overline{X}$  we have

$$E[\overline{X}] = \frac{1}{n} \sum_{i=1}^{n} E[X_i] = \frac{1}{\lambda}.$$

We know that  $\sum_{i=1}^{n} X_i \sim Gamma(n, \lambda)$ . Thus,

$$E\left[\frac{1}{\overline{X}}\right] = nE\left[\frac{1}{\sum_{i=1}^{n} X_i}\right] = \frac{n}{n-1}\lambda$$

and  $\frac{1}{\overline{X}}$  is not an unbiased estimator for  $\lambda$ .

c) With  $a_n = \frac{n-1}{n}$  we know that  $\frac{a_n}{\overline{X}}$  is an unbiased estimator for  $\lambda$ . Exercise 2: We consider the random sample  $(X_1, X_2, X_3)$ .

- a) Find expressions for
  - a)  $Y_1 = \frac{1}{4}(X_1 + 3X_2)$
  - b)  $Y_2 = \frac{1}{3}(X_1 + X_2 + X_3)$
  - c)  $Y_3 = \frac{1}{9}(2X_1 + 3X_2 + 4X_3)$

only using the variance an the expectation of  $X_1$ .

- b) Which of the statistics  $Y_1, Y_2, Y_3$  are unbiased estimators for the expectation and the population?
- c) Which estimator you would use if you had to estimate the expectation?

# Solution:

a) a)  $E[Y_1] = E[X_1]$  and  $Var(Y_1) = \frac{10}{16}Var(X_1)$ b)  $E[Y_2] = E[X_1]$  and  $Var(Y_2) = \frac{1}{3}Var(X_1)$ c)  $E[Y_3] = E[X_1]$  and  $Var(Y_3) = \frac{29}{81}Var(X_1)$ 

- b) all
- c)  $Y_2$  (smallest variance = lowest risk)

**Exercise 3:** Like in Exercise 2 we consider a random sample  $(X_1, X_2, X_3)$  and let  $Y_2$  be like in Exercise 2  $(Y_2 = \frac{1}{3}(X_1 + X_2 + X_3))$ . Compute the variance and the expectation of

- a)  $S_1 = \frac{1}{3} \{ (X_1 Y_2)^2 + (X_2 Y_2)^2 + (X_3 Y_2)^2 \}$
- b)  $S_2 = \frac{1}{2} \{ (X_1 Y_2)^2 + (X_2 Y_2)^2 + (X_3 Y_2)^2 \}$
- c) Which of the estimators  $S_1$  and  $S_2$  is an unbiased estimator for  $Var(X_1)$ ?

### Solution:

a) 
$$E[S_1] = \frac{2}{3} \operatorname{Var}(X_1)$$

b) 
$$E[S_2] = \operatorname{Var}(X_1)$$

c)  $S_2$ 

You do not have to compute the variances.

**Exercise 4:** The quality control of a company checks n products for their functionality.

- a) Based on an appropriate sample  $(X_1, \ldots, X_n)$  give an estimator for the fraction of faultily products of the whole production of the company.
- b) Verify whether the chosen estimator is unbiased and calculate the variance.

## Solution:

a)  $\hat{\pi} = Y/n$  where Y is the number of faultily products in the sample

b)

$$E[\hat{\pi}] = \frac{1}{n}np = p$$

p is the fraction of faultily products in the whole production.  $Y \sim B(n, p)$ 

$$\operatorname{Var}(\hat{\pi}) = \frac{1}{n^2} \operatorname{Var}(\mathbf{Y}) = \frac{p(1-p)}{n}$$

since  $Y \sim B(n, p)$  and therefore Var(Y) = np(1-p)

**Exercise 5:** Assume you want to determine the number of fishes in a lake, denoted as N. In order to do so, you first angle k fishes, mark them and throw them back in the lake. Now you fish until you catch a marked fish. Let  $X_1$  be the number of fishes (after having caught the fishes you throw them back in the lake.) You repeat this procedure n-times which yields the results  $X_2, \ldots, X_n$ . Assume that the probability p for catching a marked fish is p = k/N.

a) Using only  $X_1$  find an unbiased estimator for N and compute its variance.

- b) Now using  $X_1, \ldots, X_n$  find an unbiased estimator for N and compute its variance.
- c) Which estimator is better? a) or b)?

### Solution:

a) Due to the experimental set-up we know that  $X_1, X_2, \ldots, X_n \sim Geo(p)$  are independent and identically distributed. Since N = k/p we know that  $k \cdot X_1$  is an unbiased estimator for N because

$$E[k \cdot X_1] = kE[X_1] = \frac{k}{p} = N.$$

The variance of the estimator is

$$\operatorname{Var}(kX_1) = k^2 \operatorname{Var}(X_1) = \frac{k^2(1-p)}{p^2}$$

b)  $k \frac{X_1 + \dots + X_n}{n}$  is also an unbiased estimator for N since

$$E\left[k\frac{X_1+\ldots+X_n}{n}\right] = \frac{k}{n}\sum_{i=1}^n E[X_i] = \frac{k}{p} = N.$$

Due to the independency, the variance of this estimator is given by

$$\operatorname{Var}\left(k\frac{X_1 + \ldots + X_n}{n}\right) = \frac{k^2}{n^2} \sum_{i=1}^n \operatorname{Var}(X_i) = \frac{k^2(1-p)}{np^2}$$

c) Both estimators are unbiased but the second one is the better one because its variance is smaller.